



ATTACHMENT "B" - Proposal Pricing Form "Best and Final Offer"

Company Name NOBEL SYSTEMS, INC.

RFP S-1296: Provide a Computerized Maintenance Management System (CMMS)

Task	Year 1	Year 2	Year 3	Year 4	Year 5
Project Management and Work Plan (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Software Costs					
Licensing	\$63,000.00	\$63,000.00	\$63,000.00	\$63,000.00	\$63,000.00
Required modules (included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Hosting (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Third Party Components (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Data Migration (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Implementation (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
User Acceptance Testing (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Training (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Support and Maintenance (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Others Required Costs	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
GeoViewer Nearmap Integration/Configuration (Included in total cost)	\$0.00	\$0.00	\$0.00	\$0.00	\$0.00
Optional Costs-Do Not Include in Total 5-Year Cost	\$75,000.00	\$50,000.00	\$50,000.00	\$50,000.00	\$50,000.00
GeoViewer Fleet Management Module	\$35,000.00	\$25,000.00	\$25,000.00	\$25,000.00	\$25,000.00
GeoViewer Permitting Module	\$40,000.00	\$25,000.00	\$25,000.00	\$25,000.00	\$25,000.00
Total by Year	\$63,000.00	\$63,000.00	\$63,000.00	\$63,000.00	\$63,000.00
Total 5-Year Cost	\$315,000.00				
Total Not-to-Exceed Price	\$315,000.00				

By signing this form, respondent acknowledges that the cost information is accurate and represents all costs associated with performing the necessary work to satisfy the Scope of Work.

Company Name NOBEL SYSTEMS, INC.

Authorized Signature 

Printed Name and Title of Authorized Signer David Manuwa, Vice President Customer Success

Email Address davemanuwa@nobel-systems.com

Phone Number 909-963-0787 O | 909-677-5431 C